

MONOTONICITY METHODS IN PDE

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ABSTRACT. In this paper, we renormalize the huts 5.1.3 and 6.1.1 in [1], so as to be more accessible, see more details in [4]. Roughly speaking, monotonicity is the natural substitution of convexity in building solutions of PDE .

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1. **Minty-Browder method in L^2 .** In this hut, we introduce the **monotonicity method** due to Minty and Browder. As as illustrative problem, we consider the following quasi-linear PDE :

$$\begin{cases} -\operatorname{div}(\mathbf{E}(Du)) = f, & \text{in } U, \\ u = 0, & \text{on } \partial U, \end{cases} \quad (1)$$

where $\mathbf{E} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is given.

Observe that (1) can be solved by calculations of variations in case $\mathbf{E} = DF$ for some convex $F : \mathbb{R}^n \rightarrow \mathbb{R}$.

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Our problem is then what natural conditions on \mathbf{E} so that (1) may be directly tackled, when \mathbf{E} is no longer the gradient of a convex function.

This is the work of Minty and Browder, who give

Definition 1. A vector field \mathbf{E} on \mathbb{R}^n is called **monotone** if

$$(\mathbf{E}(p) - \mathbf{E}(q)) \cdot (p - q) \geq 0, \quad \forall p, q \in \mathbb{R}^n, \quad (2)$$

and show (1) can be tacitly worked out as

Theorem 2. Assume \mathbf{E} is monotone and satisfies the growth condition $|\mathbf{E}(p)| \leq C(1 + |p|)$, $p \in \mathbb{R}^n$.

Let $\{u_k\} \in H_0^1(U)$ be weak solutions of the approximating problems

$$\begin{cases} -\operatorname{div} (\mathbf{E}(Du_k)) = f_k, & \text{in } U, \\ u_k = 0, & \text{on } \partial U, \end{cases} \quad (3)$$

with $f_k \rightarrow f$ in $L^2(U)$.

Suppose $u_k \rightarrow u$ in $H_0^1(U)$. Then u is a weak solution of (1).

Proof. We first write down

$$\begin{aligned} 0 &\leq \int_U [\mathbf{E}(Du_k) - \mathbf{E}(Dv)] [Du_k - Dv] dx \quad (\text{Monotonicity}) \\ &= \int_U [f_k u_k - f_k v - \mathbf{E}(Dv)(Du_k - Dv)] dx, \quad \forall v \in H_0^1(U) \\ &\quad (\text{integration by parts and weak formulation}). \end{aligned}$$

Then taking $k \rightarrow \infty$ yields

$$0 \leq \int_U [f(u - v) - \mathbf{E}(Dv) \cdot (Du - Dv)] dx.$$

Choosing $v = u + \lambda w$, with $\lambda \in \mathbb{R}$, $w \in H_0^1(U)$ furthermore gives

$$0 \leq \operatorname{sgn}(\lambda) \int_U [\mathbf{E}(Du + \lambda Dw) \cdot Dw - fw] dx.$$

Passing $\lambda \rightarrow 0$ finally, we have as desired

$$0 = \int_U [E(Du) \cdot Dv - fw] dx, \quad \forall w \in H_0^1(U).$$

□

2. Minty-Browder method in L^∞ . We consider the strong solutions of PDE, instead of weak solutions in (1). Hence the Minty-Browder method moves from L^2 to L^∞ .

To illustrate how it works, let us consider the following fully non-linear PDE:

$$\begin{cases} F(D^2u) = f, & \text{in } U, \\ u = 0, & \text{on } \partial U, \end{cases} \quad (4)$$

where $F : S^{n \times n} \rightarrow \mathbb{R}$ is given. Here $S^{n \times n}$ is the space of real, symmetric $n \times n$ matrices.

Definition 3. The problem (4) is **elliptic**, if F is monotone decreasing with respect to matrix ordering on $S^{n \times n}$, and so

$$F(S) \leq F(R), \text{ if } S \geq R, S, R \in S^{n \times n}. \quad (5)$$

Remark 4. This very definition of ellipticity, coincides with the classical ones. In fact, we say PDE

$$Tr[A \cdot Du] = f$$

is **elliptic** if A is a non-positive definite symmetric matrix. One then readily verifies

$$\begin{aligned} S \geq R &\Rightarrow S - R \text{ non-negative definite} \\ &\Rightarrow Tr[A \cdot (S - R)] \leq 0 \\ &\Rightarrow Tr[A \cdot S] \leq Tr[A \cdot R], S, R \in S^{n \times n}. \end{aligned}$$

Now, suppose $f_k \rightarrow f$ uniformly, and consider the approximating problems

$$\begin{cases} F(Du_k) = f_k, & \text{in } U, \\ u_k = 0, & \text{on } \partial U. \end{cases} \quad (6)$$

Assume (6) has a smooth solution u_k , a priori bounded in $W^{2,\infty}(U)$.

Then, up to a subsequence,

$$u_k \rightarrow u \text{ uniformly, } D^2u_k \xrightarrow{*} D^2u \text{ in } L^\infty(U; S^{n \times n}),$$

for some u .

Our **problem** is then: does u satisfies (4)?

If F is uniformly elliptic and convex, then strong estimates are available and passing to limit is simple, see [3]. The main interest is consequently for the nonconvex F , as in hut 1.

Recall that in hut 1, the main assumption leading to the existence of a weak solution is the monotonicity inequality (2). We shall then furnish a similar monotonicity in this current circumstance, replacing the ellipticity of F .

For this purpose, we need

Proposition 5. *Let $(X, \|\cdot\|)$ be a Banach space. Then the limit*

$$[f, g] = \lim_{\lambda \rightarrow 0_+} \frac{\|g + \lambda f\|^2 - \|g\|^2}{2\lambda} \quad (7)$$

exists for all $f, g \in X$.

Proof. Writing

$$\frac{\|g + \lambda f\|^2 - \|g\|^2}{2\lambda} = \frac{\|g + \lambda f\| + \|g\|}{2} \cdot \frac{\|g + \lambda f\| - \|g\|}{\lambda},$$

we need only show that $\left\{ \frac{\|g + \lambda f\| - \|g\|}{\lambda} \right\}_{\lambda > 0}$ is bounded from below and increasing in λ . In fact, we have

1. $\frac{\|g + \lambda f\| - \|g\|}{\lambda} \geq \frac{-\lambda \|f\|}{\lambda} = -\|f\|$;
2. for $0 < \lambda < \tilde{\lambda}$,

$$\begin{aligned}
& \frac{\|g + \lambda f\| - \|g\|}{\lambda} - \frac{\|g + \tilde{\lambda} f\| - \|g\|}{\tilde{\lambda}} \\
&= \frac{\|\tilde{\lambda} g + \lambda \tilde{\lambda} f\| - \tilde{\lambda} \|g\| - \|\lambda g + \lambda \tilde{\lambda} f\| + \lambda \|g\|}{\lambda \tilde{\lambda}} \\
&\leq \frac{\|(\tilde{\lambda} - \lambda)g\| - (\tilde{\lambda} - \lambda)\|g\|}{\lambda \tilde{\lambda}} = 0.
\end{aligned}$$

□

Remark 6. In case X is a Hilbert space, $[f, g]$ is simply the inner product.

We now give an useful property of $[\cdot, \cdot]$ as

Proposition 7. The map $X \times X \ni \{f, g\} \mapsto [f, g]$ is upper semicontinuous, that is,

$$\limsup_{n \rightarrow \infty} [f_n, g_n] \leq [f, g], \quad (8)$$

for all $f, g \in X$, $f_n \rightarrow f$, $g_n \rightarrow g$ in X .

Proof. Observe that in the proof of (7), we have $\left\{ \frac{\|g + \lambda f\| - \|f\|}{\lambda} \right\}_{\lambda > 0}$ is increasing in λ , for $f, g \in X$ fixed.

Thus

$$\begin{aligned}
\limsup_{n \rightarrow \infty} [f_n, g_n] &= \limsup_{n \rightarrow \infty} \lim_{\lambda \rightarrow 0_+} \frac{\|g_n + \lambda f_n\|^2 - \|g_n\|^2}{2\lambda} \\
&= \limsup_{n \rightarrow \infty} \left\{ \lim_{\lambda \rightarrow 0_+} \left[\frac{\|g_n + \lambda f_n\| + \|g_n\|}{2} \cdot \frac{\|g_n + \lambda f_n\| - \|g_n\|}{\lambda} \right] \right\} \\
&= \limsup_{n \rightarrow \infty} \left[\|g_n\| \cdot \lim_{\lambda \rightarrow 0_+} \frac{\|g_n + \lambda f_n\| - \|g_n\|}{\lambda} \right] \\
&\leq \|g\| \cdot \limsup_{n \rightarrow \infty} \frac{\|g_n + \lambda f_n\| - \|g_n\|}{\lambda}
\end{aligned}$$

$$\leq \|g\| \cdot \frac{\|g + \lambda f\| - \|g\|}{\lambda}, \forall \lambda > 0.$$

Taking $\lambda \rightarrow 0_+$, we obtain

$$\begin{aligned} \limsup_{n \rightarrow \infty} [f_n, g_n] &= \|g\| \cdot \lim_{\lambda \rightarrow 0_+} \frac{\|g + \lambda f\| - \|g\|}{\lambda} \\ &= \lim_{\lambda \rightarrow 0_+} \frac{\|g + \lambda f\|^2 - \|g\|^2}{2\lambda} \\ &= [f, g]. \end{aligned}$$

□

Then an explicit formula in case $X = C(\bar{U})$ as

Proposition 8. *Let $X = C(\bar{U})$, then*

$$[f, g] = \max \{f(x_0)g(x_0); x_0 \in \bar{U}, |g(x_0)| = \|g\|_{C(\bar{U})}\}, f, g \in C(\bar{U}). \quad (9)$$

Proof. Denote by

$$M_h = \{x \in \bar{U}; |h(x)| = \|h\|\}, h \in C(\bar{U}).$$

Then

1. due to

$$\frac{\|g + \lambda f\|^2 - \|g\|^2}{2\lambda} \geq \frac{(g(x_0) + \lambda f(x_0))^2 - g(x_0)^2}{2\lambda} = g(x_0)f(x_0), \forall x_0 \in M_g,$$

we have

$$[f, g] \geq \text{RHS of (9)}.$$

2. for any sequence $\{\lambda_n\} \searrow 0$, $x_n \in M_{g+\lambda_n f}$,

$$\begin{aligned} \frac{\|g + \lambda_n f\|^2 - \|g\|^2}{2\lambda_n} &\leq \frac{(g(x_n) + \lambda_n f(x_n))^2 - g(x_n)^2}{2\lambda_n} \\ &= f(x_n)g(x_n) + \frac{\lambda_n}{2} f(x_n)^2 \\ &\rightarrow f(x_\infty)g(x_\infty), \text{ as } n \rightarrow \infty, \end{aligned} \quad (10)$$

for some $\bar{U} \ni x_\infty \leftarrow x_n$.

Meanwhile, taking $n \rightarrow \infty$ in

$$|g(x_n) + \lambda_n f(x_n)| = \|g + \lambda_n f\|,$$

gives

$$|g(x_\infty)| = \|g\|.$$

This together with (10) shows that

$$[f, g] \leq \text{RHS of (9)}.$$

The proof is then completed. \square

With this explicit formula for $[f, g]$, we show that monotonicity is a consequence of ellipticity as

Proposition 9. *If F is convex, then the operator $A[u] \equiv F(D^2u)$ satisfies*

$$0 \leq [A[u] - A[v], u - v], \quad \forall u, v \in C_0^2(\bar{U}). \quad (11)$$

Here $C_0^2(\bar{U})$ is the subspace of $C^2(\bar{U})$, with vanishing boundary data.

Proof. Suppose $(u - v)(x_0) = \|u - v\|_{C(\bar{U})}$, $x_0 \in U$, then

$$\begin{aligned} D^2(u - v)(x_0) &\leq 0 \\ \Rightarrow F(D^2u)(x_0) &\geq F(D^2v)(x_0) \quad (\text{by ellipticity}) \\ \Rightarrow [A[u] - A[v], u - v] &= (F(D^2u) - F(D^2v))(x_0) \cdot (u - v)(x_0) \geq 0, \end{aligned}$$

by invoking (9).

The case $(v - u)(x_0) = \|u - v\|_{C(\bar{U})}$, $x_0 \in U$ is similarly treated. \square

With all the above preparations above, we now state and prove our main result in this hut.

Theorem 10. Consider problem (4) and its approximating problems (6).

If $A[u] \equiv F(D^2u)$ satisfies the monotonicity inequality:

$$0 \leq [A[u] - A[v], u - v], \quad \forall u, v \in C_0^2(\bar{U}). \quad (12)$$

Then u solves (4) a.e..

Proof. 1. For the approximating solution $\{u_k\}$, we have

$$\begin{aligned} 0 &\leq [A[u_k] - A[v], u_k - v] \\ &\leq [f_k - A[v], u_k - v], \quad \forall v \in C_0^2(\bar{U}). \end{aligned}$$

Taking $k \rightarrow \infty$ upon a subsequence, we obtain by invoking (8) that

$$0 \leq [f - A[v], u - v], \quad \forall v \in C_0^2(\bar{U}). \quad (13)$$

2. Our strategy to prove u solves (4) is then to choose appropriate v in (13).

In fact, since $u \in W^{2,\infty}(U)$, Rademacher's theorem (see [2, 5]) implies then u is C^2 a.e.. Fix any $x_0 \in U$ where $D^2u(x_0)$ exists. We **handcraft** a C^2 function v having the form

$$v(x) \begin{cases} = u(x_0) + Du(x_0)(x - x_0) \\ \quad + \frac{1}{2}D^2u(x_0)(x - x_0, x - x_0) + \varepsilon|x - x_0|^2 - 1, & x \text{ near } x_0; \\ = 0, & x \in \partial U; \\ \in \left(u(x) - \frac{1}{2}, u(x) + \frac{1}{2}\right), & \text{otherwise.} \end{cases} \quad (14)$$

(The $\varepsilon > 0$ is chosen so that $u - v$ looks like a parabola for x near x_0 .) Then $|u - v|$ attains its maximum over \bar{U} only at x_0 . But then (13) and (9) say $(f - A[u])(x_0) \geq 0$, that is,

$$f(x_0) \geq F\left(D^2u(x_0) + 2\varepsilon I\right).$$

Sending $\varepsilon \rightarrow 0_+$, we find

$$f(x_0) \geq F(D^2u(x_0)).$$

The opposite inequality follows by replacing $\varepsilon|x - x_0|^2 - 1$ by $-\varepsilon|x - x_0|^2 + 1$ in (13). Consequently, we have

$$F(D^2u(x_0)) = f(x_0), \text{ a.e. } x_0 \in U.$$

□

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